

L Number	Hits	Search Text	DB	Time stamp
-	194	(382/152).CCLS.	USPAT; US-PGPUB	2004/03/15 15:34
-	2	WO-9942257-\$.did.	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/03/15 15:57
-	2	WO-9201539-\$.did.	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/03/15 15:57
-	6	5083073.pn. 5446835.pn. 5523663.pn. 4725965.pn. 4985846.pn. 5297238.pn.	USPAT; US-PGPUB	2004/03/15 16:09
-	33	((382/152).CCLS.) and robot	USPAT; US-PGPUB	2004/03/15 16:54
-	51	((382/151).CCLS.) and robot	USPAT; US-PGPUB	2004/03/15 16:55
-	7	arimatsu-taro.in.	USPAT; US-PGPUB	2004/03/15 16:57
-	144	watanabe-atsushi.in.	USPAT; US-PGPUB	2004/03/15 16:57
-	7	382/141-154;901/47.ccls. and watanabe-atsushi.in.	USPAT; US-PGPUB	2004/03/15 16:58
-	61	(robot) same (plural\$3 or multiple or dual or two or several or many) adj (video or camera or CCD or image or visual) same (workpiece or work-piece or work adj piece or part or model)	USPAT; US-PGPUB	2004/03/15 16:58
-	10	((382/154).CCLS.) and (reference or register\$3 or registration or teach\$3 or train\$3 or learn\$3) with (object or model or part or workpiece or work-piece or work adj piece) same robot	USPAT; US-PGPUB	2004/03/15 16:59
-	64	(robot) same (video or camera or CCD or image or visual) same (predetermined or known or specifi\$2 or determined) near distance	USPAT; US-PGPUB	2004/03/15 16:59
-	28	robot same (2-D or two-D or two-dimension\$2 or "2"-dimension\$2 or bi-dimensional or (two or "2") adj dimension\$2) with distance	USPAT; US-PGPUB	2004/03/17 09:31
-	16	robot same (reference or register\$3 or registration or teach\$3 or train\$3 or learn\$3) same (video or camera or CCD or image or visual) same (predetermined or known or specifi\$2 or determined) near distance	USPAT; US-PGPUB	2004/03/15 16:59
-	62	((901/47).CCLS.) and (registration or teach\$3 or train\$3 or learn\$3) with (model or part or workpiece or work adj piece)	USPAT; US-PGPUB	2004/03/15 16:59
-	109	(382/153).CCLS.	USPAT; US-PGPUB	2004/03/16 14:00
-	169	(382/\$.ccls. 348/\$.ccls. 356/\$.ccls. 700/\$.ccls. 901/\$.ccls.) and robot\$3 same (camera or CCD or imag\$3 or video) same (position\$3 or locat\$4 or (three or "3") adj dimension\$2 or 3D or coordinate) with (orientation or posture or attitude or pose) with (object or workpiece or work adj piece or part or bin or pile\$1 or article or body)	USPAT; US-PGPUB	2004/03/17 09:52
-	1	("5,617,335").PN.	USPAT; US-PGPUB	2004/03/17 09:52
-	1	("4,727,471").PN.	USPAT; US-PGPUB	2004/03/17 13:55

-	27	robot\$3 same (camera or CCD or imag\$3 or video) same (orientation or posture or attitude or pose) with (object or workpiece or work adj piece or part or bin or pile\$1 or article or body) same (reference or model or register\$3 or registration or template or stored) with (compar\$5 or match\$3 or correlat\$3 or correspond\$3)	USPAT; US-PGPUB	2004/03/17 13:25
-	5	JP-05127722-\$.did. JP-07270137-\$.did. JP-07319525-\$.did.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/03/18 15:21